Maritime Robotics Student Society

University of Southampton

SOUTHAMPTON SAILING
ROBOT TEAM



Sail
Servo
Sail lookup table
Wind direction

Rudder
Servo
Rudder PID
Goal heading
Current heading

Raspberry
Pi
Tack control
Waypoint heading
Goal heading

GPS
Position

IMU
Current heading
Heeling angle

Wind Sensor (IMU)

Relative wind direction Wind direction trend

Powered by:









Open Source in Open Waters: github.com/Maritime-Robotics -Student-Society/sailing-robot





Tacking figure from: http://www.physics.byu.edu/
Points of sail figure from: en.wikipedia.org/wiki/Point_of_sail